## University of Wraith Al-Anbiyaa / College of Engineering / Biomedical Engineering Department Course Description

## MODULE DESCRIPTION FORM

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Date of Preparation of this Description:					
10° MAR					
Formats:					
Fotal Units:					
S C S					
oordinator (if there are multiple names):					
ssar Ayad Ahmed qayssar.ayad@uowa.edu.iq					
<ol> <li>Building the student scientifically and qualitying him to understand the applications of digital control in some scientific and engineering fields, especially electrical and mechanical applications.</li> <li>Building and preparing the student psychologically to play his role as a reliable engineer in this field.</li> <li>Urging the student to be creative and think about specialization projects and keep pace with the development taking place in this field in terms of the basis of digital control in engineering work systems.</li> <li>Identify the types of digital control and some of their practical applications.</li> </ol>					
1. Teaching and Learning Strategy					
The main strategy that will be adopted in developing the main features of this module to encourage student's participation in the exercises, while at the same time refining and expanding their critical thinking skill. This will be achieved through classes_interactive tutorials and by considering type of simple					

		experim interest psycho	nents involving some samp ing to the students. Buildin logically to play his role as	ling activities g and prepar an engineer.	s that are ing the student
2. I	Module	Structure			
Week	Hours	Required Learning Outcomes	Unit or subject name	Learning method	Evaluation method
1-2	б	Introduction to digital engineering control systems and methods of representing systems	Introduction to Discrete-Time Control System. Review of Mathematical Foundation.	Lectures DATA SHOW	Surprise exams and classroom activitie
3-4	6	Analysis of digital control systems and design of a traditional digital controller	Analysis of Discrete-Time Systems. Design of Conventional Discrete- Time Controllers.	Lectures DATA SHOW	Surprise exams and classroom activitie
5-6	6	Introduction to theory state space	State-space modeling	Lectures DATA SHOW	Surprise exams and classroom activitie
7-8	6	How to analyze using the method (controllability and observability)	controllability and observability	Lectures DATA SHOW	Surprise exams and classroom activitie
9-10	6	the definition, z- transform And analysis methods	Sampling theorem Z-transform	Lectures DATA SHOW	Surprise exams and classroom activitie
11-12	6	How to design a digital controller using state-space method	Design of digital control systems using state-space methods	Lectures DATA SHOW	Surprise exams and classroom activitie
13-14	6	Recognition digital PID controllers	Digital PID controllers and tuning	Lectures DATA SHOW	Surprise exams and classroom activitie
<u>Module</u> Quizzes	Evaluatio (4%), As	on signment (3%), lab. (10	0%), attendance (3%), Mid exa	n (30%), FINA	L exam (50%)

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Learning and Teaching Resources.					
	1- Modern Control Engineering, (5th Edition) By: Katsuhiko				
Description of the sector of the	Ogata. Mechanical Engineering, University of Minnesota.				
(curricular books, if any)	2- Control Systems Engineering, (6th Edition) By: Norman S.				
(curricular coolis, ir any)	Nise. Electrical and Computer Engineering Department at				
	California State Polytechnic University.				
Main references (sources)	Modern Control Engineering, (5th Edition)				
Recommended books and	1- Internet files.				
references (scientific	2- All solid scientific journals and sites that are related to the broad				
journals, reports)	concept of engineering control				
Electronic References	Tracking Scientific websites to view recent developments in the prescribed				
Websites	subject For fifth year students.				
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